Hybrid neural network approach for predicting maintainability of object-oriented software

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Abstract. Estimation of different parameters for object-oriented systems development such as effort, quality, and risk is of major concern in software development life cycle. Majority of the approaches available in literature for estimation are based on regression analysis and neural network techniques. Also it is observed that numerous software metrics are being used as input for estimation. In this study, object-oriented metrics have been considered to provide requisite input data to design the models for prediction of maintainability using three artificial intelligence (AI) techniques such as neural network, Neuro-Genetic (hybrid approach of neural network and genetic algorithm) and Neuro-PSO (hybrid approach of neural network and Particle Swarm Optimization). These three AI techniques are applied to predict maintainability on two case studies such as User Interface System (UIMS) and Quality Evaluation System (QUES). The performance of all three AI techniques were evaluated based on the various parameters available in literature such as mean absolute error (MAE) and mean Absolute Relative Error (MARE). Experimental results show that the hybrid technique utilizing Neuro-PSO technique achieved better result for prediction of maintainability when compared with the other two.

Keywords: Artificial neural network, software metrics, Genetic algorithm, maintainability, Neurons, Particle swarm optimization, QUES, UIMS.

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1 Introduction

Maximum amount of cost is always associated with any software product over its lifetime during software maintenance period. One of the approaches for controlling maintenance costs is to utilize software metrics during the development phase [2]. A number of metrics are available in literature to evaluate the quality of software [6][1][13]. In practice, reliability and maintainability play a major role to meet quality. Reliability is generally measured in terms of the number of faults found in the developed software during a particular time period. Maintainability is typically measured in terms of effort given for change. Change effort can mean either the average effort to make a change to a class or component or connector or configuration, or the total effort spent on changing these elements.

Metrics-based maintainability prediction helps to reduce future maintenance efforts by enabling developers, identifying the determinants of software quality, and improving quality of design or coding. It also provides managers with information for more effective planning of valuable resources [19]. In order to predict the maintainability of a different elements (Object, Class, Method, etc.), several statistical methods are available in literature. But less importance has been given on use of machine learning techniques. Artificial intelligence techniques, a subset of machine learning methods have the ability to measure the properties...
of a class of object-oriented software, that human beings recognize as intelligent behavior. These methods are able to approximate the non-linear function with more precision. Hence they can be applied for predicting maintainability in order to achieve better accuracy. In this paper, ANN with gradient descent learning method \[\text{model}\], hybrid approach of neural network and particle swarm optimization such as Neuro-PSO \[\text{technique}\], and hybrid approach of ANN and genetic algorithm such as Neuro-genetic (Neuro-GA) \[\text{technique}\] techniques are used for maintainability prediction on two commercial software product such as User Interface System (UIMS) and Quality Evaluation System (QUES). To train these models, object-oriented software metrics are considered as input data.

The remainder of the paper is organized as follows: Section 2 shows the related work in the field of software maintainability estimation and object-oriented metrics. Section 3 highlights on research background related to this study. Section 4 briefs about the methodologies used to estimate the maintainability. Section 5 highlights on the results for maintainability prediction, achieved by applying ANN, Neuro-GA, and Neuro-PSO techniques. Section 6 represents a comparison on the performance of the designed models based on the different performance parameters. In Section 7 threats to validity have been discussed and Section 8 concludes the paper with scope for future work.

2 Related work

It is observed in literature that software metrics are used in design of prediction models which serve the purpose of computing the prediction rate in terms of accuracy such as fault, effort, re-work, and maintainability.

In this work, the use of software metrics for maintainability prediction has been emphasised. Table 1 shows the summary of literature review on maintainability; where it describes the applicability of numerous software metrics available in literature in designing respective prediction models. Table 1 also shows the different prediction models used in literature for predicting maintainability.

From Table 1 we interpreted that many of the authors have used statistical methods such as regression based analysis and their different deviations in predicting the maintainability. But keen observation reveals that very less work has been carried out on application of neural network models for designing their respective prediction models. Neural network models over the years have seen an explosion of interest, and applicability across a wide range of problem domain. Indeed, these models can be mainly used to solve problems related to prediction and classification and act as efficient predictors of dependent as well as independent variables due to its special modeling technique where in they posses the ability to model complex functions. In this paper, software metrics have been considered for predicting maintainability by applying three artificial intelligence techniques, based on neural network applications.

3 Research background

The following subsections highlight on the data set used for predicting maintainability. Data normalization and cross-validation methods have been considered to obtain better accuracy, and then dependent and independent variables are chosen for models to be applied for maintainability estimation.

3.1 Metrics set

Metrics suites are defined for different goals such as effort estimation, fault prediction, and maintainability. In this paper, different object-oriented metrics have been considered for predicting maintainability of object-oriented software. Maintainability is measured as the number of changes made to the code during a maintenance period. A line change can be an ‘addition’

<table>
<thead>
<tr>
<th>Author</th>
<th>Software Metrics used</th>
<th>Prediction model</th>
</tr>
</thead>
<tbody>
<tr>
<td>Li and Henry</td>
<td>CK metrics, Li and Henry metrics, and Size Metrics.</td>
<td>Regression based models.</td>
</tr>
<tr>
<td>Paul Oman et al.</td>
<td>Halstead’s metrics, McCabe metrics.</td>
<td>Regression based models.</td>
</tr>
<tr>
<td>Binkley et al. (1998)</td>
<td>CDM and design quality metrics.</td>
<td>Regression based models.</td>
</tr>
<tr>
<td>Bandi et al. (2003)</td>
<td>Interface metrics and design quality metrics.</td>
<td>variance, correlation, and regression based models.</td>
</tr>
</tbody>
</table>

Table 1: Summary of Empirical Literature on Maintainability
### Table 2: Definition of the metrics used [13]

<table>
<thead>
<tr>
<th>Metric</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Weighted method per class (WMC).</td>
<td>Sum of the complexities of all class methods.</td>
</tr>
<tr>
<td>Depth of inheritance tree (DIT).</td>
<td>Maximum length from the node to the root of the tree.</td>
</tr>
<tr>
<td>Number of children (NOC).</td>
<td>Number of immediate sub-classes subordinate to a class in the class hierarchy.</td>
</tr>
<tr>
<td>Response for class (RFC).</td>
<td>A set of methods that can potentially be executed in response to a message received by an object of that class.</td>
</tr>
<tr>
<td>Lack of cohesion among methods (LCOM).</td>
<td>Measures the dissimilarity of methods in a class via instanced variables.</td>
</tr>
<tr>
<td>Message-passing coupling (MPC).</td>
<td>The number of send statements defined in a given class.</td>
</tr>
<tr>
<td>Data abstraction coupling (DAC).</td>
<td>The number of abstract data types defined in a given class.</td>
</tr>
<tr>
<td>Number of methods (NOM).</td>
<td>The number of methods implemented within a given class.</td>
</tr>
<tr>
<td>SIZE1.</td>
<td>The number of semicolons in a given class.</td>
</tr>
<tr>
<td>SIZE2.</td>
<td>Total number of attributes and local methods in a given class.</td>
</tr>
</tbody>
</table>

or ‘deletion’ of lines of code in a class [13]. The metrics selected in this study are tabulated in Table 2.

### 3.2 Effectiveness of metrics

Once the maintenance data values are determined, an attempt is made to establish a relationship between the maintainability and the metrics. Hence in this approach, change is considered as a dependent variable and each of the software metrics as an independent variable while developing the relation. Maintainability is thus assumed to be a function of WMC, DIT, NOC, RFC, LCOM, MPC, DAC, NOM, SIZE1, and SIZE2, and is represented as:

$$
Maintainability = f(WMC, DIT, NOC, RFC, LCOM, MPC, DAC, NOM, SIZE1, SIZE2) $$

### 3.3 Case study

In this paper, to analyze the effectiveness of the proposed approach, the data sets (metric values) of two commercial software system used by Li and Henry (1993) are considered as case studies [13]. Software systems such as User Interface System (UIMS) and Quality Evaluation System (QUES) are chosen for computing the maintainability, which are developed using Classic-Ada language. Classic-Ada is an object-oriented programing language that adds the capability of object-oriented programing to Ada by providing object-oriented construct in addition to the Ada constructs [13]. Classic-Ada metrics analyzer has been used to gather metrics from Classic-Ada’s design and source code. The data set for over three years is being considered for our analysis. UIMS and QUES software system have 39 and 71 classes respectively.

### 3.4 Descriptive statistics

This subsection highlights on the descriptive statistics of maintainability data. The metric values of the UIMS and QUES systems comprising the CK metric suite, Li & Henry, SIZE, and Change metrics, which in turn constitute the data set for the respective software systems along with their descriptive statistics such as Min, Max, Median, Mean, and Standard deviation are tabulated in Table 3.

In this analysis, we disregarded the CBO metric of the CK metrics suite for computing maintainability as it measures “non-inheritance related coupling” [6]. Also the derivative of inheritance metric ‘NOC’ in QUES software product, has all its 71 classes with NOC values as zero. This indicates that there are no immediate sub-classes of a class in the class hierarchy and hence NOC is not considered in computing maintainability in this analysis. From Table 3 we understood that the DIT metric has low value of median and mean for both UIMS and QUES data sets. The low value of median and mean for DIT shows that inheritance is not being used in both software system. Similarly medians and means of NOM and SIZE2 are found in the UIMS and QUES data sets and they suggest that the class size at the design level in both systems are similar. However, the medians and means of SIZE1 in the QUES data set are significantly larger than those in the UIMS data set. This suggests that the complexities of the problems processed by the two systems are rather different. Moreover, the medians and means of RFC and MPC in the QUES data set are of greater value in comparison
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Table 3: Descriptive statistics of classes for UIMS and QUES [13]

<table>
<thead>
<tr>
<th></th>
<th>UIMS</th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>WMC</td>
<td>DIT</td>
<td>NOC</td>
<td>RFC</td>
<td>LCOM</td>
<td>MPC</td>
<td>DAC</td>
<td>NOM</td>
<td>SIZE1</td>
<td>SIZE2</td>
</tr>
<tr>
<td>Max.</td>
<td>69</td>
<td>4</td>
<td>8</td>
<td>101</td>
<td>31</td>
<td>12</td>
<td>21</td>
<td>40</td>
<td>439</td>
<td>61</td>
</tr>
<tr>
<td>Min.</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>2</td>
<td>1</td>
<td>1</td>
<td>0</td>
<td>1</td>
<td>4</td>
<td>1</td>
</tr>
<tr>
<td>Median</td>
<td>5</td>
<td>2</td>
<td>0</td>
<td>17</td>
<td>6</td>
<td>3</td>
<td>1</td>
<td>7</td>
<td>4</td>
<td>9</td>
</tr>
<tr>
<td>Mean</td>
<td>11.38</td>
<td>2.15</td>
<td>0.94</td>
<td>23.20</td>
<td>7.48</td>
<td>4.33</td>
<td>2.41</td>
<td>11.38</td>
<td>106.44</td>
<td>13.97</td>
</tr>
<tr>
<td>Std Dev</td>
<td>15.89</td>
<td>0.90</td>
<td>2.01</td>
<td>20.18</td>
<td>6.10</td>
<td>3.41</td>
<td>4.00</td>
<td>10.21</td>
<td>114.65</td>
<td>13.47</td>
</tr>
<tr>
<td></td>
<td>QUES</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Max.</td>
<td>83</td>
<td>4</td>
<td>0</td>
<td>156</td>
<td>33</td>
<td>42</td>
<td>25</td>
<td>57</td>
<td>1009</td>
<td>82</td>
</tr>
<tr>
<td>Min.</td>
<td>1</td>
<td>0</td>
<td>0</td>
<td>17</td>
<td>3</td>
<td>2</td>
<td>0</td>
<td>4</td>
<td>115</td>
<td>6</td>
</tr>
<tr>
<td>Median</td>
<td>9</td>
<td>2</td>
<td>NA</td>
<td>40</td>
<td>5</td>
<td>17</td>
<td>2</td>
<td>6</td>
<td>211</td>
<td>10</td>
</tr>
<tr>
<td>Mean</td>
<td>14.95</td>
<td>1.91</td>
<td>0</td>
<td>54.38</td>
<td>9.18</td>
<td>17.75</td>
<td>3.44</td>
<td>13.41</td>
<td>275.58</td>
<td>18.03</td>
</tr>
<tr>
<td>Std Dev</td>
<td>17.05</td>
<td>0.52</td>
<td>0</td>
<td>32.67</td>
<td>7.30</td>
<td>8.33</td>
<td>3.91</td>
<td>12.00</td>
<td>171.60</td>
<td>15.21</td>
</tr>
</tbody>
</table>

3.5 Data normalization technique

Normalization of input feature values has been carried out, over the range [0,1], so as to adjust the defined range of input feature values and avoid the saturation of neurons. In literature, techniques such as Min-Max normalization, Z-Score normalization, and Decimal scaling are available for normalizing the data. In this study, we consider Min-Max normalization technique to normalize the data [10]. Min-Max normalization technique has been considered in this study because it has the advantage of preserving exactly all relationships in the data, which is usually not possible to avail using other similar techniques. It performs a linear transformation on the original data. After applying Min-Max normalization, each attribute will lie within the range of [0,1] values and it will remain same. Min-Max normalization is calculated by using the following Equation:

\[ \text{Normalized}(x) = x' = \frac{x - \text{min}(X)}{\text{max}(X) - \text{min}(X)} \quad (2) \]

where \( \text{min}(X) \) and \( \text{max}(X) \) represent the minimum and maximum values of the attribute \( X \) respectively.

3.6 Cross-validation method

Cross-validation is a statistical learning method which is used to evaluate and compare the models by partitioning the data into two portions. One portion of the divided set is used to train or learn the model and the rest of the data is used to validate the model.

K-fold cross-validation is the basic form of cross validation [12]. In K-fold cross-validation the data are first partitioned into \( K \) equal (or nearly equally) sized portions or folds. For each of the \( K \) model, \( K-1 \) folds are used for training and the remaining one fold is used for testing purpose. The significance of K-fold-cross-validation lies in it's ability to use the data set for both training and testing. So the performance of each model on each fold can be tracked using predetermined performance metrics available in literature. In literature, it is observed that 5-fold and 10-fold cross-validation approaches have been used for designing a model. In this paper, 10-fold cross-validation is used in QUES and 5-fold cross-validation is used in UIMS for comparing the models, i.e., data sets are divided into 10 and 5 parts in QUES and UIMS respectively (each fold in both QUES and UIMS contain seven number of data samples).

4 Techniques for predicting Maintainability

The subsequent subsections highlight on the use of artificial intelligence techniques (AI) for predicting maintainability [3][14]. These AI techniques are:

- 1. Artificial neural network (ANN) with Gradient descent learning method [3][14].
- 2. Hybrid approach of ANN and genetic algorithm (Neuro-GA (NGA) and Adaptive Neuro-GA (ANGA)) [5].
- 3. Hybrid approach of ANN and Particle Swarm Optimization (Neuro-PSO (NPSO) and Modified Neuro-PSO (MNPSO)) [18].
predicting maintainability using object-oriented metrics
for two software products UIMS and QUES. Figure 1 shows
the architecture of ANN, which contains three
layers, namely input layer, hidden layer, and output
layer.

Input layer  Hidden layer  Output layer

Figure 1: Artificial neural network

Here, for input layer, linear activation function is
used, and for hidden layer and output layer, sigmoidal
function or squashed-S function is used.

Neural network can be represented as:

\[ Y' = f(W, X) \]  \hspace{1cm} (3)

where \( X \) is the input vector, \( Y' \) is the output vector, and
\( W \) is the weight vector. The weight vector \( W \) is updated
in every iteration so as to reduce Mean Square Error
(MSE). MSE is calculated using following equation

\[ MSE = \frac{1}{n} \sum_{i=1}^{n} (y_i' - y_i)^2 \]  \hspace{1cm} (4)

where \( y \) is the actual output and \( y' \) is the expected output.

Different methods are available in literature to up-
date weight vector ‘W’ such as Gradient descent, New-
ton’s method, Quasi-Newton method, Gauss Newton
conjugate-gradient method, and Levenberg Marquardt
method etc. In this study, we considered Gradient des-
cent method for updating the weight vector ‘W’ be-
cause, although the convergence of Gradient descent
method is stable, but the computation complexity is low
as compared with other methods.

Gradient descent learning method is used for updat-
ing the weights during learning phase. It uses first-
order derivative of total error to find the minima in error
space. Normally Gradient vector \( G \) is defined as the
1st order derivative of error function \( E_k \), and the error
function is represented as:

\[ E_k = \frac{1}{2}(y_k' - y_k)^2 \]  \hspace{1cm} (5)

Gradient vector \( G \) is represented as:

\[ G = \frac{\partial E_k}{\partial W} = \frac{1}{2} \frac{\partial (y_k' - y_k)^2}{\partial W} \]  \hspace{1cm} (6)

After obtaining the value of gradient vector \( G \) in
each iteration, weighted vector \( W \) is updated as:

\[ W_{k+1} = W_k - \alpha G_k \]  \hspace{1cm} (7)

where \( W_{k+1} \) is the updated weight, \( W_k \) is the current
weights, \( G_k \) is gradient vector, \( \alpha \) is the learning con-
stant, \( y \) and \( y' \) are the actual and expected output
respectively.

4.2 Neuro-Genetic (NGA) Approach

In this approach, genetic algorithm is used for updat-
ing the weight during learning phase. A neural network
with a configuration of ‘l-m-n’ has been considered
for estimation, i.e., the network consists of ‘l’ number
of input neurons, ‘m’ number of hidden neurons, and
‘n’ number of output neurons. In this paper, for input
layer, linear activation function is used, and for hidden
layer and output layer, sigmoidal function or squashed-
S function is used.

The number of weights \( N \) required for this network
with a configuration of ‘l-m-n’ can be computed using
the following equation:

\[ N = (l + n) \times m \]  \hspace{1cm} (8)

with each weight (gene) being a real number and
assuming the number of digits (gene length) in weights
to be \( d \). The length of the chromosome \( L \) is computed
using the following equation:

\[ L = N \times d = (l + n) \times m \times d \]  \hspace{1cm} (9)

For determining the fitness value of each chromo-
some, weights are extracted from each chromosome
using the following equation:

\[ W_k = \begin{cases} 
\frac{1}{10^{d-2}}x_{kd+1} & \text{if } 0 \leq x_{kd+1} < 5 \\
\frac{1}{10^{d-2}}x_{kd+2} + x_{kd+3} + 10^{d-3} + \ldots + x_{(k+1)d} & \text{if } 5 \leq x_{kd+1} \leq 9 \\
\frac{1}{10^{d-2}}x_{kd+2} + x_{kd+3} + 10^{d-3} + \ldots + x_{(k+1)d} & \text{if } x_{kd+1} > 9
\end{cases} \]  \hspace{1cm} (10)

The fitness value of each chromosome is computed
using following equation:

\[ F_i = \frac{1}{E_i} = \frac{1}{\sqrt{\sum_{j=1}^{N} E_{ij}}} = \frac{1}{\sqrt{\sum_{j=1}^{T_{ji}} O_{ji}}} \]  \hspace{1cm} (11)

where \( N \) is the total number of training data set, \( T_{ji} \)
and \( O_{ji} \) are the estimated and actual output of input
instance \( j \) for chromosome \( i \).
In this approach, PSO is used for updating the weight during learning phase. PSO is a population based search algorithm. In this paper PSO is used as back propagation algorithm to train the network. A neural network with a configuration of ‘l-m-n’ is considered for estimation, i.e., the network consists of ‘l’ number of input neurons, ‘m’ number of hidden neurons, and ‘n’ number of output neurons. In this paper, for input layer, linear activation function is used, and for hidden layer and output layer, sigmoidal function or squashed-S function is used. PSO encodes the parameters of neural networks as particles and the population of particles are referred as swarm. Here, the synaptic weights of the neural network are initialized to as particles and the PSO is applied to obtain the optimized set of parameters. In NPSO, initially particle swarm is generated with random velocity (V) and position (X), where

\[
P_i = N \times \text{random function}
\]

Velocity (V) and position (X) of particles are updated using Equations (15) and (16) respectively.

\[
V_{k+1}^i = V_k^i + C_1 R_1(Pbest_k^i - X_k^i) + C_2 R_2(Gbest_k^i - X_k^i)
\]

\[
X_{k+1}^i = X_k^i + V_{k+1}^i
\]

where

- \(V_{k+1}^i\) and \(X_{k+1}^i\) are the updated velocity and position.
- \(V_k^i\) and \(X_k^i\) are the current velocity and position.
- Pbest and Gbest are the local and global best position respectively.
- \(C_1\) and \(C_2\) are positive constants, usually they range between one to four.
- \(R_1\) and \(R_2\) are two random function whose values lies in between zero to one.

Figure 3 shows the block diagram for NPSO approach, which represents the steps followed to design the estimation model.

Figure 2: Flow chart representing Neuro-GA execution

4.3 Adaptive Neuro Genetic (ANGA) Approach

To overcome the limitations of genetic algorithm such as premature convergence due to local optima and low convergence speed, an attempt has been made towards the improvement of parameters such as cross over probability \((P_c)\) and mutation probability \((P_m)\). In this paper \((P_c)\) and \((P_m)\) values are adaptively decreased to prevent disruption of any proper solution. \((P_c)\) and \((P_m)\) values are updated using Equations (12) and (13). After implementation, it was observed that Adaptive Neuro-GA Approach yields better result in comparison with Neuro-GA.

\[
(P_c)_{k+1} = (P_c)_i - \frac{C_1 \times n}{7}
\]

\[
(P_m)_{k+1} = (P_m)_i - \frac{C_2 \times n}{7}
\]

where \((P_c)_{k+1}\) and \((P_m)_{k+1}\) are the updated probability of cross over and mutation, \((P_c)_i\) and \((P_m)_i\) are the initial probability of cross over and mutation, \(C_1\) and \(C_2\) are positive constant and \(n\) is the number of chromosomes having same fitness value.

4.4 Neuro Particle Swarm Optimization (NPSO) Approach

Neuro Particle Swarm Optimization is a hybrid approach of neural network and Particle Swarm Optimization [13]. In this approach, PSO is used for updating the weight during learning phase. PSO is a population based search algorithm. In this paper PSO is used as back propagation algorithm to train the network. A neural network with a configuration of ‘l-m-n’ is considered for estimation, i.e., the network consists of ‘l’ number of input neurons, ‘m’ number of hidden neurons, and ‘n’ number of output neurons. In this paper, for input layer, linear activation function is used, and for hidden layer and output layer, sigmoidal function or squashed-S function is used. PSO encodes the parameters of neural networks as particles and the population of particles are referred as swarm. Here, the synaptic weights of the neural network are initialized to as particles and the PSO is applied to obtain the optimized set of parameters. In NPSO, initially particle swarm is generated with random velocity (V) and position (X), where

\[
\frac{E_i}{E} = \frac{1}{\sqrt{\sum_{i=1}^{N} E_i}}
\]

Velocity (V) and position (X) of particles are updated using Equations (15) and (16) respectively.

\[
V_{k+1}^i = V_k^i + C_1 R_1(Pbest_k^i - X_k^i) + C_2 R_2(Gbest_k^i - X_k^i)
\]

\[
X_{k+1}^i = X_k^i + V_{k+1}^i
\]

where

- \(V_{k+1}^i\) and \(X_{k+1}^i\) are the updated velocity and position.
- \(V_k^i\) and \(X_k^i\) are the current velocity and position.
- Pbest and Gbest are the local and global best position respectively.
- \(C_1\) and \(C_2\) are positive constants, usually they range between one to four.
- \(R_1\) and \(R_2\) are two random function whose values lies in between zero to one.
Random particle swarms is generated with random position (X) and velocity (V)

Fitness value is computed using Equation 14

Position is updated using Equation 15

Particle velocity is calculated using Equation 15

Fitness (X) > Pbest ?

Pbest is replaced by X

Fitness (X) > Gbest ?

Gbest is replaced by X

Stopping criterion met ?

Yes

No

Model is used for testing

Figure 3: Flow chart representing PSO execution

incorporated just before the completion of one generation. In this paper $(P_m)$ value is adaptively decreased to prevent disruption of very good solution. $(P_m)$ value is updated using Equation 17

$$(P_m)_{k+1} = (P_m)_i - \frac{C * n}{10} \quad (17)$$

where $(P_m)_{k+1}$ is the updated probability of mutation, $(P_m)_i$ is the initial probability of mutation, and $n$ is the generation number.

5 Implementation

In this section, the relationships between value of metrics and maintainability of the classes are determined. Software metrics are considered as input nodes of neural networks and the output obtained is the computed maintainability of the object-oriented software. Accuracy of estimation for Maintainability for the model designed by using different AI techniques is determined by using performance evaluation parameters such as mean relative error (MRE) [9] and mean absolute relative error (MARE) [9]. Parameters like True error ($\hat{e}$) and estimate of true error ($\hat{\hat{e}}$) are being used for evaluating models involving cross validation approach [11].

The following sub-sections give a brief note on implementation details of the applied neural network techniques.

5.1 Artificial neural network (ANN) model

In this paper, architecture of ANN with three layers, i.e., input layer, hidden layers and output layers is considered, in which nine nodes in QUES and ten nodes in UIMS act as input nodes, the number of hidden nodes vary from nine to twenty and one node acts as an output node. Software metrics are considered as input and output is the computed maintainability of the object-oriented software. The network is trained using Gradient descent learning method.

Gradient descent learning method is used for updating the weights using Equation 7. True error and estimate of true error determine the suitable model to be chosen for predicting maintainability. The hidden node with least deviation between true error and the estimate of true error in each fold is chosen as suitable model for estimation. Figure 4 depicts the distribution of the hidden nodes of the suitable model in each fold for UIMS and QUES case studies. The final model chosen for predicting maintainability is based on the median values of the hidden nodes in their respective folds.

From Figure 4 the median value for all the 10 folds in QUES and 5 folds in UIMS is found to be ‘12’ and ‘11’ respectively. The median value determines the final model to be designed based on the number of hidden nodes. After identifying, the suitable model, i.e., model having ‘11’ number of hidden neurons in UIMS and ‘12’ number of hidden neurons in QUES is evaluated. Next, the model is trained using gradient descent learning method unless and until the neurons achieve the threshold value of ‘MSE’ or reach stopping criterion of 1,000 epochs. Table 4 shows the various performance parameters for UIMS and QUES software system respectively. Table 4 reports that the high value of Pearson’s correlation (‘r’) in case of UIMS is found.

Figure 4: Number of hidden nodes in each fold
to be 0.9675, which is an indication that both actual and estimated maintainability values are strongly dependent in a linear fashion on each other. But in case of QUES, Pearson’s correlation (‘r’) is 0.7382, which is an indication that both actual and estimated maintainability values are not too much linearly dependent. So this model of predicting maintainability does not yield comparably good result for QUES dataset.

<table>
<thead>
<tr>
<th></th>
<th>r</th>
<th>Epochs</th>
<th>MAE</th>
<th>MARE</th>
</tr>
</thead>
<tbody>
<tr>
<td>UIMS</td>
<td>0.9675</td>
<td>549</td>
<td>0.0997</td>
<td>0.4252</td>
</tr>
<tr>
<td>QUES</td>
<td>0.7382</td>
<td>1,000</td>
<td>0.1340</td>
<td>0.4363</td>
</tr>
</tbody>
</table>

Figure 5 shows the variance of MSE verses number of iterations for UIMS and QUES system respectively. Figure 6 depicts the closeness between the actual and estimated maintainability of UIMS and QUES.

5.2 Neuro-genetic (Neuro-GA) approach

In this paper, 1-m-1 configuration of neural network is considered, i.e.,

- UIMS consists of 10 input nodes, 09-20 varying hidden nodes and one output node. The total number of weights used in 10-m-1 configuration model are determined using equation 8, i.e., $(10 + 1) \times m = 11 \times m$ (where ‘m’ represents the number of hidden nodes varying from nine to twenty)

- QUES consists of 9 input nodes, 9-20 varying hidden nodes and one output node. The total number of weights used in 9-m-1 configuration model are determined using equation 8, i.e., $(9 + 1) \times m = 10 \times m$ (where ‘m’ represents the number of hidden nodes varying from nine to twenty)

Each weight is considered as a gene of length 5, so the length of one chromosome is calculated using Equation 18.

$$L = \begin{cases} (10 + 1) \times m \times 5 = 55 \times m & \text{For UIMS} \\ (9 + 1) \times m \times 5 = 50 \times m & \text{For QUES} \end{cases}$$

In this study a population of size 50 is considered, i.e., initially 50 chromosomes are randomly generated. The input-hidden layer and hidden-output layer weights of the network are computed using Equation 10. In case of NGA, two-point cross-over operation is performed on the generated population, i.e., probability of crossover is constant. If probability of cross over $(P_c)$ and probability of mutation $(P_m)$ values are considered to be constant, it may so happen that, as the generation progress towards global optima, any solution giving better result may get disrupted and may move to higher fronts by which the approach may take huge amount of time to converge. Due to this reason, Adaptive neuro genetic approach (ANGA) has been considered. In ANGA, $P_c$ and $P_m$ values are adaptively decreased to prevent disruption of solutions with better result. $(P_c)$ and $(P_m)$ values are updated using Equations 12 and 13. In this paper, initially $(P_c)$ and $(P_m)$ values are chosen as 0.8 and 0.2 respectively. Constant $C_1$ and $C_2$ values are chosen as 0.1 and 0.01 respectively.

The execution of the algorithm terminates when 95% of the chromosomes achieve same fitness values. True error and estimate of true error determine the suitable model to be chosen for predicting maintainability. The hidden node with least deviation between true error and the estimate of true error in each fold is chosen as 0.1 and 0.01 respectively.

From Figure 7, the median value for all the 10 folds in QUES is found to be ‘12’ in case NGA and ‘15’ in case of ANGA, and the median value for all the 5 folds in UIMS is found to be ‘11’ in case of NGA and ‘13’ in case of ANGA. The median value determines the final model to be designed based on the number of folds in UIMS is found to be ‘11’ in case of NGA and ‘13’ in case of ANGA. The median value determines the final model to be designed based on the number of
hidden nodes. Next, the model is trained using Neuro-GA method unless and until 95% of the chromosomes achieve same fitness values or reach maximum iteration limit (of 200 epochs). Table 5 shows the various performance parameters for two products. Table 5 reports that the high value of pearson’s correlation (r) in case of UIMS and QUES, which is an indication that both actual and estimated maintainability are strongly linear dependence on each other. From Table 5, it is evident that ANGA Approach achieved better performance as compared to NGA.

Table 5: Performance matrix

<table>
<thead>
<tr>
<th></th>
<th>Product</th>
<th>r</th>
<th>MAE</th>
<th>MARE</th>
</tr>
</thead>
<tbody>
<tr>
<td>NGA</td>
<td>UIMS</td>
<td>0.9500</td>
<td>0.0832</td>
<td>0.3329</td>
</tr>
<tr>
<td></td>
<td>QUES</td>
<td>0.9647</td>
<td>0.1481</td>
<td>0.3380</td>
</tr>
<tr>
<td>ANGA</td>
<td>UIMS</td>
<td>0.9804</td>
<td>0.1023</td>
<td>0.2442</td>
</tr>
<tr>
<td></td>
<td>QUES</td>
<td>0.8696</td>
<td>0.1468</td>
<td>0.3133</td>
</tr>
</tbody>
</table>

Figure 8 shows the variance of number of chromosomes having same fitness value and generation number of UIMS and QUES. From Figure 8, it is evident that NGA consumes more generation to achieve the threshold value. Figure 9 depicts the closeness between the actual and estimated maintainability of UIMS and QUES.

5.3 Neuro Particle Swarm Optimization (NPSO) Approach

In this approach a population of size 50 is considered, i.e., initially a swarm of 50 particles are generated with random position and velocity. After each generation, velocity and position of particles are updated using Equations 15 and 16 respectively. In MNPSO, the initial probability of mutation ($P_m$) is considered as 0.2, its constant value is taken as 0.01. They are updated using Equation 17. The randomly generated particles undergo mutation. The training process is same as that of NPSO, but a mutation phase is incorporated just before the completion of one generation. The execution of the algorithm continues until 100 generation.

we chose True error and estimate of true error to determine the suitable for predicting maintainability. The hidden node with least deviation between true error and the estimate of true error in each fold is chosen as suitable model for estimation. Figure 10 depicts the distribution of the hidden nodes of the suitable model in each fold. The final model chosen for predicting maintainability is based on the median values of the hidden nodes in their respective folds.

From Figure 10, the median value for all the 10 folds in QUES is found to be ‘15’ in case NPSO and MNPSO. The median value for all the 5 folds in UIMS is found to be ‘14’ in case of NPSO and ‘13’ in case of MNPSO. Median values determine the final model to be designed based on the number of hidden nodes. After identifying, the suitable model, the model is trained...
using NPSO and MNPSO approaches up to 100 generation. Table 6 shows the various performance parameters for two products. Table 6 reports that from the higher value of Pearson’s correlation (‘r’) in case of UIMS and QUES, here is an indication that both actual and estimated maintainability are strongly linear dependence on each other. From Table 6, it is evident that MNPSO Approach achieves better performance as compare to NPSO Approach.

Table 6: Performance matrix

<table>
<thead>
<tr>
<th>Product</th>
<th>r</th>
<th>MAE</th>
<th>MARE</th>
</tr>
</thead>
<tbody>
<tr>
<td>NPSO</td>
<td>UIMS</td>
<td>0.9850</td>
<td>0.1030</td>
</tr>
<tr>
<td></td>
<td>QUES</td>
<td>0.8618</td>
<td>0.1490</td>
</tr>
<tr>
<td>MNPSO</td>
<td>UIMS</td>
<td>0.9805</td>
<td>0.0790</td>
</tr>
<tr>
<td></td>
<td>QUES</td>
<td>0.9832</td>
<td>0.1320</td>
</tr>
</tbody>
</table>

The line in the middle of each box represents the median of the Pearson’s residual. In case of UIMS, all the approaches have a median residual value close to zero, but in case of QUES data set except ANN approach, all other approaches have a median residual close to zero. Of all the approaches considered, MNPSO approach has the narrowest box, small sized whiskers, and few number of outliers. Based on these boxplots, it is evident that the model designed by using MNPSO approach obtained the best estimation accuracy as compared to other approaches.

This paper also presents a comparative analysis of the proposed work with the work done by Li and Henry [13]. In their analysis, Li and Henry [13] have used only two performance parameters such as R-Square and Adjusted R-Square to compare the designed models. In this study also R-Square and Adjusted R-Square have been used for comparison. Table 7 shows the comparative results of the proposed work with that of related work [13] based on R-Square and Adjusted R-Square values. R-Square measures the percentage of the variance in the dependent variable accounting for independent variables in the regression model based on the sample data. Adjusted R-Square measures the percentage of the variance in the dependent variable accounting for independent variables in the regression model based on the population.

Table 7 reports that, when compared with the performance parameters values for ‘R-Square’ and Adjusted R-Square for the two software products namely UIMS and QUES with respect to the work of Li and Henry [13], the proposed Modified Neuro-PSO (hybrid approach of neural network and PSO) obtained better prediction rate of maintainability.

In literature, mostly statistical methods such as regression based analysis and simple neural network such as ANN have been considered to design a model for
predicting maintainability. Other techniques such as Neuro-Genetic (hybrid approach of neural network and genetic algorithm) and Neuro-PSO (hybrid approach of neural network and Particle Swarm Optimization) have not yet been applied for predicting maintainability [16]. Yuming Zhou et al. [19] and Van Koten et al. [17] have used same UIMS and QUES software system for predicting maintainability based on different regression and simple neural network models. They have considered ‘MMRE’ as a performance parameter to compare the models designed for predicting maintainability of object-oriented software systems. Table 8 shows the MMRE value of the proposed work and the work done by Yuming Zhou et al. [19] and Van Koten et al. [17].

Table 8 reports that, in case of QUES software MMRE value obtained is almost same but in case of UIMS software, the proposed approach obtained better prediction rate for maintainability.

7 Threat to Validity

Several issues affect the results of the experiment are:

- Two object-oriented systems, i.e., UIMS and QUES used in this study are design in ADA language. The models design in this study are likely to be valid for other object-oriented programming language such as Java or C++. Further research can extend to design a model for other development paradigms.

- In this study, only eleven set of software metrics are used to design a models. Some of the metrics which are widely used for object-oriented software are further considered for predicting maintainability.

- We only consider AI techniques for designing the prediction models to predict maintainability. Further, we can extend the work to reduce the feature using feature reduction techniques such as PCA, RST, statistical test, etc..

8 Conclusion

In this paper, we propose a prediction models to predict maintainability of object-oriented software using software metrics. Gradient descent, Neuro-GA, Adaptive Neuro-GA, Neuro-PSO and Modified Neuro-PSO approaches have been applied to design a model by employing 10-fold cross-validation technique for QUES and 5-fold cross-validation technique for UIMS on varying size of hidden neurons. These techniques have the ability to predict the output based on historical data. The software metrics are used as requisite input data to train the models and estimate the number of changes made in the code during maintenance period. The results reveal that the modified Neuro-PSO prediction approach obtained low values of MAE and MARE, when compared with gradient descent prediction and Neuro-GA model. These low values of performance parameters emphasize on qualitative prediction model obtained in the estimation analysis. Also this comparative analysis highlights that there exists a strong relation between software metrics and maintainability.

Further, work should be replicated to other system...
like open source projects and service oriented system using different AI techniques in order to analyze which model performs better in achieving higher accuracy for maintainability prediction. Also, work can be extended on the usage of feature reduction techniques such as rough set and principal component analysis to minimize the computational complexity of the input data set.

References


